

# **Characterization of 3D Printed Stainless Steel SS316L Powders Joined by TIG-, Plasma- and Laser Welding**

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**Original Article** 

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#### *Abstract*

Additive manufacturing or 3D printing is becoming more and more common in industry fabrication, especially for spare parts which cannot be found easily on the local market and for tailor made parts. For large parts and due to its size limitations, it is sometimes required to join 3D printed parts with other 3D printed parts or conventionally produced parts. In this work, 3D printed flat plates 4mm thick were prepared by direct laser sintering of SS316L powders. Mechanical properties and microstructure were investigated. Elongation and maximum tensile stress of 3D printed flat plates are with 1.3% and 704MPa smaller than the values 2% and 1241MPa of cold-rolled SS316 parts. The 3D printed flat plates were joined by welding using TIG welding, plasma welding and laser welding. The welded joints were tested for their mechanical properties and microstructure. For the used welding conditions, the fracture occurred outside the weld zone. The maximum stress of the welded parts is 65-80% of 3D printed flat plates. The elongation of the welded parts is above 3%.

## 1- INTRODUCTION

3D printing (or additive manufacturing) is a form of rapid prototyping technology which allows for the fabrication of 2 or 3 dimensional products via a layer by layer materials build-up method. Its relevance as a mainstream tool for series production has grown significantly over the past 10 years[1]. While, 3D printing techniques remain less competitive to conventional (subtractive) manufacturing methods (such as milling, grinding, cutting, casting, rolling, etc.) in terms of high volume production, it brings along a profound advantage in terms of the possibility of easily fabricating complex geometry components and the customization of components to be deployed to highly specialized engineering systems. Such a technical merit brings 3D printing technologies to an industrial foreground where its application alongside other manufacturing techniques is being explored. There are five most widely applied forms of 3D printing techniques ; namely, fused deposition modeling (FDM), stereolithography (SLA), inkjet printing, laminated object manufacturing (LOM), selective laser melting (SLM) and selective laser sintering (SLS). Each of these methods is unique in the sense that the kinds and forms of materials used as feedstock as well as the approach to materials build-up into a threedimensional form are different. For metal processing, the SLM and SLS methods are applied. These methods use a laser source to fuse together metallic powder particles in a layer by layer fashion until a dense part is built-up. By altering the beam parameters (power, flux etc.) and scan strategies (rate, direction etc.), new and unusual, even nonequilibrium microstructures can be produced; including controlled microstructural architectures which ideally extend the contemporary materials science and engineering paradigm relating structure-properties-processingperformance<sup>[2-4]</sup>. For 3D printed parts, the importance of testing on essentially every part cannot be over stressed, especially since 3D printing technology has still not been fully technically assessed and characterized<sup>[5]</sup>. To understand the technical capabilities of 3D printed parts, the systematic examination and testing of parts need to be conducted. The main tests are carried out using tensile testing, hardness and microhardness testing and others depending on the application of the product. Among the properties measured are the modulus of elasticity, yield point, ultimate tensile strength and ductility. These can be obtained from the tensile test applied on samples with standard shape and dimensions. Hardness and microhardness tests give an indication about the resistance to surface scratching and wearing of the material<sup>[6]</sup>. Furthermore, the product size and dimensions of 3D printing are restricted by the size of the platform of each 3D printing machine (typically a surface area no more than 300mmx500mm, and a height of about 600mm), which is not large enough for big parts. Therefore, in order to produce large components, a solution could be to subdivide the component into several parts then to join these parts together. The joining of metallic parts is a key process in technical practice. Welding, fasteners (nuts and bolts) as well as application of adhesive bonds are the main joining methods applied in industry. These methods account for a huge portion of investment in engineering construction. For instance, welding is an essential manufacturing step in the automotive and aerospace industries. It provides both joining and repair value in these industries. Very few information is available in the literature on how to

**Table 1:** Welding parameters.

use joining techniques on 3D printed parts and the kind of mechanical properties and microstructure induced at the joint zones. Comparison of welded wrought and SLM parts have been studied by Casalino *et al.*<sup>[7]</sup> and Järvinen<sup>[8]</sup>.

The primary goal of this study is to see the influence of the welding process on the weld properties of steel samples prepared by SLM. Microstructural examination as well as the mechanical test on the welded parts will be correlated to the 3D printing conditions thus allowing for the determination of the optimal conditions for producing good weld joints of the studied materials.

#### 2- SAMPLE PREPARATION

The preparation of the samples consists of several steps such as 3D printing, welding and preparation for characterization which are explained in the following. A summary of the samples is given in Table 1.

micro-melting and welding of fine powder particles in stacked layers until the complete part is built. The process is based on sintering powder as squares 5mm x 5mm randomly on the surface. This process depends strongly on the process parameters to get high strength and crack free products. Here, the parameters applied are: laser power 200W, scanning speed 800mm/min, line overlap 30%, focus diameter 0.15 mm, scanning islands 5mmx5mm, and layer thickness 50µm. The specimens were built with an



### 3D printing

3D printing of the samples was performed at a rapid prototyping machine "M3 linear concept laser" located at Central Metallurgical Research and Development Institute (CMRDI). The specimens were produced from SS316L powders. The SS316L powder was purchased from powder manufacturer in China and the chemical composition was determined as shown in Table2 below. The apparent density was between 3.5g/cm3 and 5g/cm3 . The particle size is determined by 400 mesh which is translated into a layer size of 50µm. The 3D process uses laser for the

 $Table$ 

layer size of $50\mu m$ . The 3D process uses laser for the						orientation angle of 45° relative to the base.					
<b>able 2:</b> Chemical composition of SS316L powder											
Fe	N	Si			Cu	Mn		Mo	Ni	Cr	
Rest	0.10	0.75	0.010	0.0025	0.50	2.00	0.03	2.50	14.00	18.00	

#### Welding

The samples are welded by TIG, plasma welding and laser welding as shown in Fig. 1. The welding processes TIG and plasma welding are done on two phases. The first stage (pilot arc) is usually done with higher energy than the normal welding arc as to initiate the molten zone in the weld to proceed. This pilot arc usually takes fraction of second and is in the range of 100-110A for TIG welding and then

goes down to about 50-60A. For plasma welding, the pilot arc is about 70A and then goes down to 45A during the constant state welding. For the second paths, the welding for the high sample thickness is done by two welding paths (root and cap). The nozzle had a size  $\varnothing$ 2.4mm. The welding wire was GGS1.4576, ENISO14343-A:W 19 12 3 Nb Si with chemical composition of C:0.06, Si:0.80, Mn:1.40, Cr:19.00, Ni:12.00, Mo:2.60, Nb:0.7 and diameter



of 1.6mm. Yield strength and elongation are 450MPa and 30%, respectively. Laser welding was done with CO2-laser RS6000 with handling from Balliu, welding speed:1300mm/min, power:1100W (35% activation with small opening, Gaussian power distribution, shielding and working gas:He20L/min, optic: off-axis-parabolic mirror, focal length:150mm. The process conditions for welding with its specific welding parameters are summarized in Table1.



**Fig. 1:** Welding regions produced by TIG welding (left), plasma welding (middle) and laser welding (right).

#### Microstructure investigation

In order to examine the microstructure of the specimen, it had to be prepared for observation under the optical microscope. The welded samples and broken samples from the tensile test were mounted in Bakelite through compression mounting. The mounted samples were wet ground using different grades of silicon carbide grinding paper from P60 through P180, P360, P360, P800, and P1000 to finally P1200. This process was followed by polishing using polycrystalline diamond suspension gel.

An etchant constituting of equal parts water, nitric acid and hydrochloric acid was used to etch the polished sample. Microstructure was observed before and after etching using an optical microscope.

#### Tensile test

For tensile testing, dog-bone shapes according to ASTME8/E8M-13a specimen specification were prepared. They have a total length 60mm, neck length 20mm, total width 12mm, neck width 6mm and thickness 4mm. The samples were not produced directly at dog-bone shape during 3D printing because welding has to be done on straight sections. Therefore, the samples received by 3D printing were cut to dog-bone shape for tensile testing after welding. Straight sections have been cut with diamond cutter and remaining parts were removed with machining. The tensile strength of the samples were measured by Zwick/Roell machine Z100. The specimens were fixed with wedge screw holders. A macro extensometer was used. The test speed was 5mm/min.

#### Hardness measurements

The Vickers hardness test equipment (Zwick/Rowell) was set to a loading of 15kg and 20kg to get HV15 and HV20.

#### Corrosion measurements

Open circuit potential (OCP) and potential cyclic voltammetry (PCV) experiments were conducted with Voltalab 10 PGZ 100 (www.radiometer - analytical.com, Figure 2) to determine the electrochemical corrosion rate (ECR). The corroding solution was aqueous sodium chloride NaCl 3.5%. Reference electrode was saturated calomel electrode SCE and auxiliary electrode Platinum.



**Fig. 2:** Microstructure of TIG welding of sample T3. (a) Overview with 5000µm scale bar before and after etching, (b) HAZ with 500µm scale bar, (c) weld region with 500µm scale bar.

#### 3- RESULTS AND DISCUSSION

SLS has been used as an additive manufacturing method to produce specimens from stainless steel powder. These specimen have been welding by three different welding processes ; namely, TIG welding, plasma welding and laser welding. The welding regions for the three processes are shown in Figure 1. At first, the microstructure of the samples is discussed. Then, hardness profiles and tensile test results are given. The observation of the macrostructure indicates that the welding regions look differently depending on the welding process as shown in Figures 2-4. The overviews reveal a size of the welding region with the heat effected zone (HAZ) of more than 5mm for TIG welding and plasma welding, whereas the size is less than 1mm for laser welding. The HAZ is 1-2mm wide for TIG welding and plasma welding, but only 0.1mm for laser welding. These results are expected as the laser welding is known to have a deep penetration and very small HAZ. The base material shows the structure of the 3D printing process with the lines of laser melting. The 3D printed steel contained some oxides and cavities due to the melting of powders. After etching, the typical austenitic stainless steel microstructure was observed. The microstructure of the weld cross-sections shows more dense and pore-free weld region compared to the base material, denoting a successful weld. There is some excess material above the weld zone for all welding processes due to deposited filler material. The HAZ has less porosity than the base material and the building structures of 3D printing are less pronounced than in the base material due to the transformation by the induced heat.

In TIG welded sample, T3 dentritic structures are visible in the weld zone (Fig. 2). In the welding zone, small particles of 1µm diameter appear. Two phases are visible which seem to come from powder and filler.

For plasma welded sample P3, no dentritic structures have been seen in the welded zone indicating less energy

input than for T3. Plasma welded sample P2 shows more fine pores in the base material than P3. There is a dentritic structure in the weld zone. The structure of the two phases is finer than in sample T3. For plasma welded sample P1a, the weld region is framed by a thin line. This thin line consists of very fine structures of gray phase. Some dentrites are visible but not in the whole welding zone.



**Fig. 3:** Microstructure of plasma welding of sample P1b. (a) Overview before and after etching with  $5000 \mu m$  scale bar, (b) HAZ with 500µm scale bar, (c) weld region with 500µm scale bar.

For laser welded sample L1 a clear welding centerline is visible (Fig. 4). There is some excess material outside the weld. The weld zone is about 1.2mm wide at the top and 0.3mm wide in the bottom. In summary, the welded region shows dendritic structures and no porosity.



**Fig. 4:** Microstructure of laser welding of sample L1. (a) Overview with 2000µm scale bar, (b) base material with 500µm scale bar, (c) weld region with 500 $\mu$ m scale bar and (d) weld and HAZ with 200µm scale bar.

Mechanical properties were tested by hardness profiles and tensile tests. Points of hardness measurements with the indenter are visible in Fig. 5. Hardness decreases in the weld region for all welding conditions. For TIG welding and plasma welding the hardness HV15 decreased from 230-250 in the base material to 160-190 in the weld region. The hardness in the HAZ is between these values. For laser welding, the hardness HV20 is about 230 in the

base material and 225 in the weld region. This hardness decrease is less pronounced than for plasma welding and TIG welding. That the hardness of the weld zone is below the hardness of the SLM produced base material was also observed by Casalino *et al*[7]. This could result from the difference in chemical composition of the filler with respect to the base material and to the difference in cooling rates



**Fig. 5:** Hardness evaluation at embedded welded sample with hardness indentations (a) and hardness profiles of the samples L1, T1, T2 (b) and T3, P1, P2, P3 (c). Regions of base material (base), heat effected zone (HAZ) and weld are indicated in (c).

During tensile tests, fracture occurred in the base material as shown in Fig. 6. The results of tensile tests such as maximum stress and elongation are summarized in Table 3. The maximum stress of all samples is almost in between hot rolled and cold rolled values found in literature. The highest values of ultimate tensile stress (UTS) have been found for the base material and the laser welded sample. The laser welding showed with 9% a higher elongation than the base material. The TIG welded sample had an intermediate maximum stress of 539MPa and an elongation of 4.5%. The plasma welded samples had a maximum stress in the range of 453MPa – 563MPa and an elongation of 3.8% - 8.3%. The maximum stress increased with welding current for plasma welded samples.



Fig. 6: Front and backside of fractured samples after tensile tests, a) TIG weld sample T3, b) plasma welded sample P3.





**Table 3:** Results of tensile tests.

Corrosion tests have been done in the weld region and compared to corrosion outside the weld region for TIG welded sample T3. The corrosion in the weld/HAZ zone is with 0.6µm/yr smaller than the corrosion of the base material with about 2µm/yr. The method of welding effects greatly the macrostructure, the microstructure, the extent of heat effected zone and the mechanical properties. The laser welding shows highest tensile strength, ductility and hardness.

#### 4- CONCLUSION

Stainless steel samples were successfully prepared by 3D direct laser melting of powders. The samples were welded by TIG, plasma and laser welding. The weld zone was free of pores in all welds. The strength of the laser weld reached 700MPa with 9% elongation, while plasma and TIG welds resulted in lower strength and ductility with a strength of 453-563MPa with elongations of 3.8-8.3% for plasma welds and 539MPa with 4.5% elongation for TIG weld. The corrosion rate was lower in the TIG weld with  $0.6\mu$ m/yr than in the base metal with  $2\mu$ m/yr. For effective joining of small parts with thicknesses below 4mm, a laser power of 1100W has proven to achieve a complete welding penetration in one path and the welding process was reproducible. In case of plasma and TIG welding, the process needs to be automated or semi-automated to achieve reproducible results. It would be useful to carry out more mechanical testing to characterize additive manufactured materials and their welds further. Fatigue tests and residual stresses measurements are planned in the future.

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